### **FEATURES**

The TCR-C smart electric actuators are intended for motorising ¼ turn valves with a torque of 20, 50 or 90 Nm. **Smart function**: the manoeuvring time is adjustable. With a compact construction and plastic housing, they are especially well suited for motorising small size ball valves. IP67 leak-tightness: to be used indoors and, possibly, outdoors under a shelter. Possible installation in parallel. Manual control with a key. As an option, the actuator can take a third position. (see § 3<sup>rd</sup> position).

### **AVAILABLE MODELS**

Supply voltages: 230V AC, 24V AC/DC.

### **LIMITS OF USE**

IP Code	IP 67
Ambient temperature	- 20°C / +60°C
Service factor	S4-50%

### **MECHANICAL FEATURES**

Gear box	treated steel pinions
Torques	20 - 50 - 90 Nm
Angle of rotation	90° +/- 2°
Declutching	Without
Override control	By key



Actuator	TCR 02C		TCR 05C		TCR 11C	
Torques (Nm)	20	20	50		90	
Voltage	24V AC - DC	95-265V AC-DC	24V AC - DC	95-265V AC-DC	24V AC - DC	95-265V AC-DC
Manoeuvring time (s)	10	10	12	12	10	10
ISO 5211:	F03/F04/F05 - star 11		F05/F07 - star 14		F05/F	07 - star 17

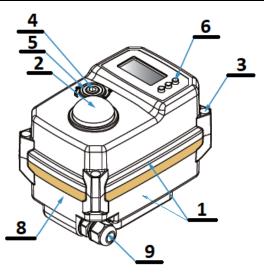
### **ELECTRICAL FEATURES**

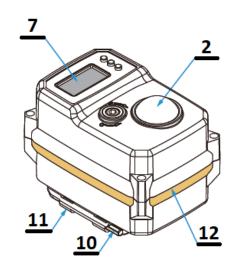
Actuator	TCR 02C	TCR 05C	TCR 11C		
Motor protection	Thermal switch				
Limit switches	2 adjustable switches				
Auxiliary switches	2 adjustable dry switches				
Anti-condensation	integrated				
Electrical connection	PE M10 + 1.5m cable	PE M20 + 1.5m cable	2 x PE M14		

Actuator	TCR 02C		TCR 05C		TCR 11C	
Voltage	24V AC - DC	95-265V AC-DC	24V AC - DC	95-265V AC-DC	24V AC - DC	95-265V AC-DC
Power (W)	15	15	25	25	100	100
Current (A)	0,35	0,035 - 0,075	0,83	0,035 - 0,075	2,5	0,26 - 0,52
Fuse protection (A)	2	1	4	2	5	2

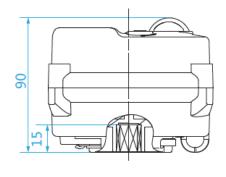
## **CONSTRUCTION** (TCR-02C)

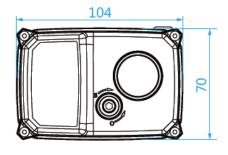
TCR-02C					
No. Name Material No. Name Material					
1	Casing + lid	Plastic (ABS)	7	1.3" LCD display	OLED
2	Position indicator	Polycarbonate plastic	8	Rating plate	PVC
3	Screw x 4	Aisi 304	9	Packing gland	Nylon
4 Backup control stem Aisi 304 10 Hex key Steel					
5 Gasket NBR 11 Key support Plastic (ABS)		Plastic (ABS)			
6	Adjustment button	Rubber	12	Cover gasket	NBR
		Weight (	kg): 0.6	20	



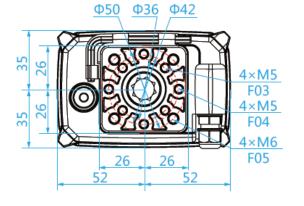


## **DIMENSIONS (mm)**



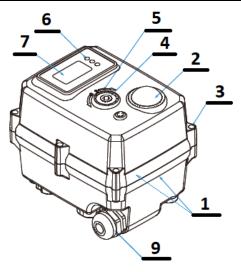


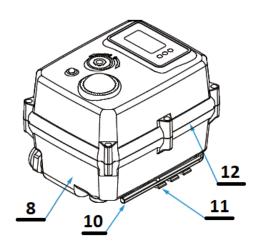




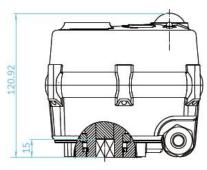
## **CONSTRUCTION** (TCR-05C)

TCR-05C						
No.	No. Name Material No. Name Material					
1	Casing + lid	Plastic (ABS)	7	1.3" LCD display	OLED	
2	Position indicator	Polycarbonate plastic	8	Rating plate	PVC	
3	Screw x 6	Aisi 304	9	Packing gland	Nylon	
4 Backup control stem Aisi 304 10 Hex key Steel						
5 Gasket NBR 11 Key support Plastic (ABS)		Plastic (ABS)				
6	Adjustment button	Rubber	12	Cover gasket	NBR	
	Weight (kg): 1.800					

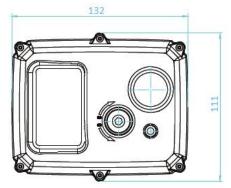


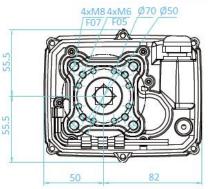


## **DIMENSIONS (mm)**



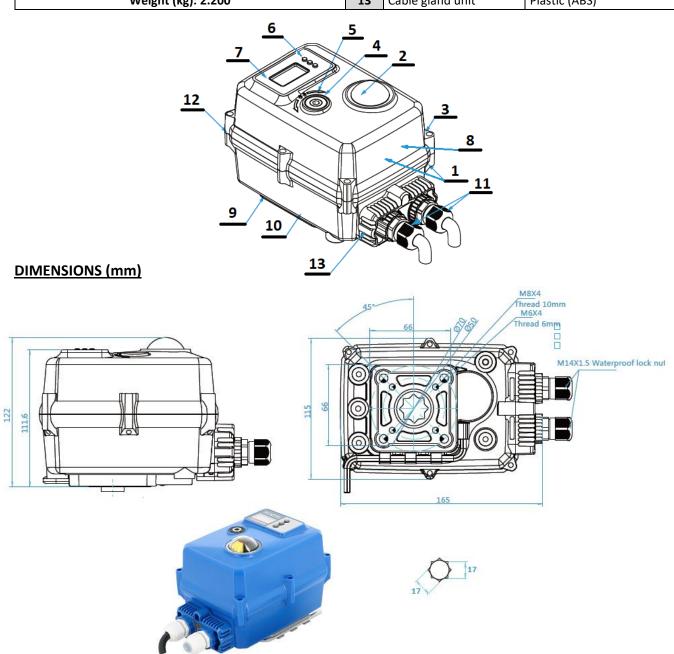




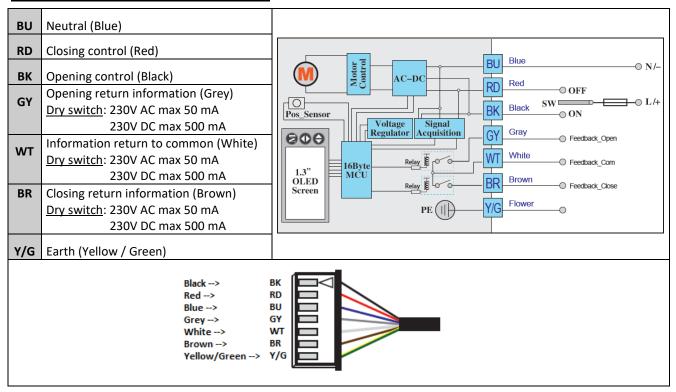


## **CONSTRUCTION** (TCR-11C)

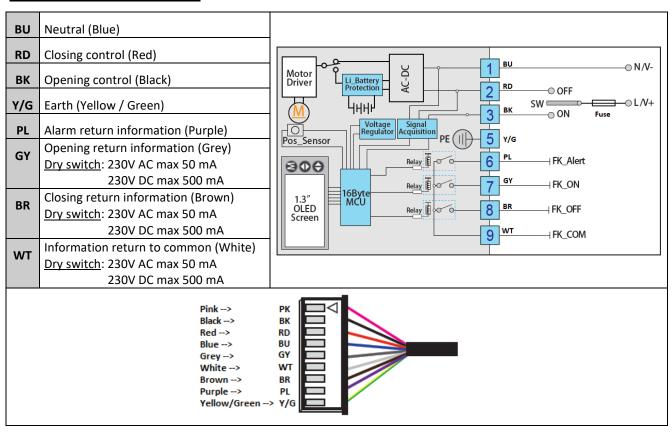
	TCR-11C					
No.	Name	Material	No.	Name	Material	
1	Casing + lid	Plastic (ABS)	7	1.3" LCD display	OLED	
2	Position indicator	Polycarbonate plastic	8	Rating plate	PVC	
3	Screw x 6	Aisi 304	9	Key support	Plastic (ABS)	
4	Backup control stem	Aisi 304	10	Hex key	Steel	
5	Gasket	NBR	11	X 2Packing gland	Nylon	
6	Adjustment button	Rubber	12	Cover gasket	NBR	
	Weight (kg): 2.200		13	Cable gland unit	Plastic (ABS)	



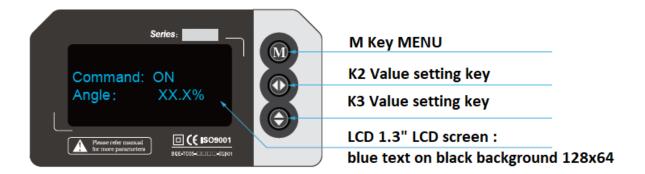
#### WIRING DIAGRAM (TCR 02C / TCR 05C)



#### **WIRING DIAGRAM (TCR 11C)**



## **DESCRIPTION OF THE 1.3" LCD SCREEN**



### **ACTUATOR SETTINGS**

The following functions can have their parameters set from the menu accessible on the screen:

STEP	TITLE	FUNCTION AND VALUES				
1	Entering the menu	Press the "M" button for more than 5 s.				
2		Press the "M" button for more than 5 s. Enter the code "333" (use the keys K2 and K3) Press again the button "M"				
2 Enter the password	UserSET: PassWord: XXX					
3 Dead band	Dead band	This function is used to set the accuracy and the sensitivity of the control: the larger the band, the lower the accuracy; the narrower the band, the more oscillating the system can be.  Setting range: 0.1 to 9.9% - Setting by default: 1%				
		UserSET: DeadZone: X.X%  UserSET: DeadZone: 0.1%				
4	Hysteresis adjustment	This parameter setting is a prerequisite for the next.  YES = adjustment is possible  NO = no adjustment is possible (value by default)				
4		UserSET: IsGO_Hyste: NO  UserSET: IsGO_Hyste: YES				

5	Hysteresis value	If the previous parameter is "YES", it is possible to set the hysteresis value between 0.1 and 12%. The value by default is 0.5%. Do not use the function if there is a play between the valve's stem and the actuator's square.  UserSET: Hysteres: X.X%  UserSET: Hysteres: 9.0%
6	Slight adjustment of the closed position	It is possible to change the closed position of the automatic valve, by a few degrees. This function is interesting if a leak is found along the line. Press key K3 to decrease the opening angle 0.1° (down to -8.5° max) and K2 to (up to -8,5° max). Press key M to move to the next parameter.  UserSET:  CIPOS_Adj: X.X°  Offset-Open  UserSET:  CIPOS_Adj: X.X°  Offset-Close  UserSET:  CIPOS_Adj: X.X°  This is minimum  UserSET:  CIPOS_Adj: X.X°  This is maximum
7	Manual adjustment of the speed of rotation	This function is used for slowing down the motor.  Range: 20-100% - Value by default = 100%  UserSET: Speed_PUL: XX% UserSET: Speed_PUL: 100% This is maximum UserSET: Speed_PUL: 5% This is minimum
8	Setting the operating speed	It is possible to set the operating speed of the actuator to 5 to 100% of the rated speed. The value by default, is 100%. Press key K3 to increase the speed (max 100%) or K2 to decrease it (min 5%). Press key M to move to the next parameter.  N: it is not recommended to combine functions 5 and 6, the actuator could become overcharged.  UserSET:  Speed_PWM: 100%
9	Response time	Used to set the response speed of the valve. The smaller the value, the less sensitive the control. The bigger the value, the more sensitive it is. Increase the value when the response speed is too low.  Setting range: 1x20x – Value by default 3x  UserSET: StallTime: 3X  UserSET: StallTime: 20X maximum

10	Parameter setting for the 3 <sup>rd</sup> position	This function is accessible only on an actuator with a "B33" option (see last §).  For the TRC-C standard model, the parameter setting is not available.  UserSET: B33Posi: 50%
11	Inverting the opening and closing controls	The parameter setting is used to invert the opening and closing controls. The B33 parameter setting is not affected.  Parameter setting by default: "NO"  UserSET: CMD_Swap: Yes
12	Actuator's position when SW1 (RED) and SW2 (BLACK) are engaged	This parameter setting is available only the B33 version: 4 different positions can have their parameters set: open, closed, unchanged or 3 <sup>rd</sup> position  Parameter setting by default: KEEP  UserSET: BothIN_ON: KEEP  UserSET: BothIN_ON: OFF  UserSET: BothIN_ON: B33
13	Actuator's position when SW1 (RED) and SW2 (BLACK) are disengaged	This parameter setting is available only the B33 version: 4 different positions can have their parameters set: open, closed, unchanged or 3 <sup>rd</sup> position  Parameter setting by default: KEEP  UserSET: Both IN_OFF: KEEP  UserSET: Both IN_OFF: OFF  UserSET: Both IN_OFF: B33
14	Checking the feed signal	The actuator periodically tests its electrical power supply. A change of a value will change the interval between two tests. In current use, there is no need to change this parameter.  UserSET: PDChk_Time: 100%

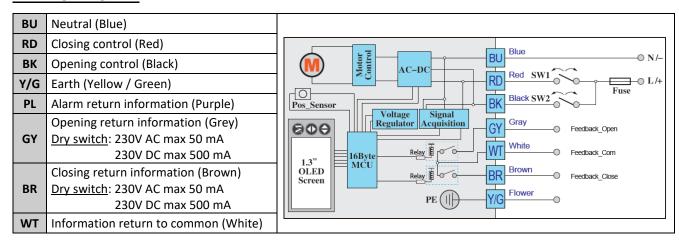
45	Power supply position by default	This parameter setting is not available on the standard version  Parameter setting by default: KEEP
15		UserSET: UserSET: PDAction: KEEP PDAction: OFF PDAction: ON
16	Super capacitor charge	This parameter is not available on the standard version  Value by default: 95%
16	Super-capacitor charge	UserSET: BatCharge: XX%  UserSET: BatCharge: 60% Mininum  UserSET: BatCharge: 99% Maxinum
	Actuator locking after the intervention of the supercapacitor	This parameter is not available on the standard version  Value by default: UNLOCK
17		UserSET: MotLock: LOCK  UserSET: MotLock: UNLOCK
		English or Mandarin
18	Choice of language	UserSET: DisMode: English UesrSET: DisMode: Chinese
19	Alarm test	This function is used to control whether a defect alarm is broadcast or not. It is especially used for factory testing  Value by default: ON
		UserSET: Test Alarm: ON
20	Eviting the many	Press K3 to exit the menu The system will switch back in the automatic checking mode.
20	Exiting the menu	UserSET: ExitSET: Push K3

### THE OPTION 3RD POSITION "B33"

The "B33" option is used to provide a third position, other than the "open" and "closed" position. The percentage of opening of the third position is set from the parameter setting menu. On the side of control, the programming of taking the 3 positions is carried out as follows:

SW1	SW2	Actuator position	Returns from limit switches
Engaged	Disengaged	0°	WT connected with BN
Disengaged	Engaged	90°	WT connected with GY
Engaged	Engaged	Can be set from 10% to 220% of the opening, i.e. between 9° and 198° of opening.	WT connected with GY and BN

#### WIRING DIAGRAM



### **TROUBLESHOOTING**

Defect met	Cause of defect	Method of solving	
	Non-connected electrical grid.	Connect to the electrical grid.	
	Wrong voltage.	Check the actuator's voltage.	
Inactive actuator	Motor overheating.	Check the torque on the valve.	
	Faulty connection.	Check the connection to the terminal box.	
	Damaged start capacitor.	Contact the supplier for repair.	
No switch signal	Faulty connection.	Check the connections.	
No switch signal	Damaged microswitch	Change the microswitch	
Valve that is not fully	Use the return signal from the actuator check.	Receiving a return signal does not mean that the actuator is fully closed, hence do not cut the power supply.	
closed	The hysteresis increases due to wear or between the actuator and the valve's stem.	Readjust the limit cams. Contact the supplier for repair.	
	Unsuitable cable cross-section being used.	Contact the supplier for repair.	
Presence of humidity or	The cable connection is not leak-tight.		
water in the actuator	Worn sealing gaskets.		
	Loose cover screws.	Dry the internal parts and tighten the cover screws.	